

AVL TECHNOLOGIES

MODEL 1612K AvL Carbon Fiber 1.6 METER MOTORIZED VEHICULAR SNG ANTENNA



Reflector	1.6 meter AvL Carbon-Fiber
Feed	Mode-matched with Horn R/J
Optics	Offset, Prime Focus, .8 f/d
Az/EI Drive System	AvL Cable Drive Positioner
Mount Geometry	Elevation over Azimuth
Polarization Adjustment	Rotation of Feed OMT

Electrical RF



Frequency
Gain (Midband)
R/T
4-port

VSWR
Beamwidth (degrees)
-3 dB
-10 dB

First Sidelobe Level (Typical)
Radiation Pattern Compliance
Antenna Noise Temperature
Polarization

Power Handling Allowed
Cross-Pol Isolation

On-Axis (minimum)
Off-Axis (within 1 dB BW)

Feed Port Isolation – TX to RX
Satellite system Compliance

Receive

10.95-12.75 GHz

43.7 dBi
43.6 dBi
1.30:1

1.1
1.8
-26 dB

6 dB Typ better than FCC §25.209, ITU-R S.528.5
40° K at 30° Elevation

Linear Orthogonal standard, Optional Co-pol
1000w at TX Port

35 dB
25 dB
35 dB

FCC, Intelsat, Eutelsat, AsiaSat

Transmit

13.75-14.5 GHz

46.0 dBi Typical, 45.5 dBi Min
45.4 dBi
1.30:1

1.0
1.6
-30 dB

6 dB Typ better than FCC §25.209, ITU-R S.528.5
40° K at 30° Elevation

Linear Orthogonal standard, Optional Co-pol
1000w at TX Port

35 dB
35 dB
80 dB (includes filter)

Controllers

Standard

Three-axis Jog Control & Display with Auto-stow

Optional Upgrades

Semi-automatic Operation

Drive to calculated position based on operator entered vehicle location, heading, plus satellite (longitude or listed) Drive to calculated position based on auto GPS and Flux-Gate Compass data and satellite peaking with LNB signal

Automatic Operation

One-button acquisition of selected satellite including peaking and optimization of cross-pol (certified for auto-commissioning on most satellite services)

Auto-acquisition

Size

2 Rack Units (complete electronics) or 1 RU (with antenna mounted electronics) Options

Input Power

110/240 VAC, 1 ph, 50/60 Hz, 8/4A peak, 1A continuous

AVL TECHNOLOGIES

MODEL 1612K AvL Carbon Fiber 1.6 METER MOTORIZED VEHICULAR SNG ANTENNA

Mechanical

Az/EI Drive System	AvL Cable Drive System
Polarization Drive System	Non Back-driving Worm Gear
Travel	
Azimuth	400°
Elevation	True elevation readout from calibrated inclinometer
Mechanical	0° to 90° of boresight (no cowling or boom mounted BUC)
Electrical	Standard limits at 5° to 65° (CE Approval) or 5° to 90°
Polarization	±95° for 2-port and 3-port Feeds ±50° for 2-port Wideband and 4-port feeds
Speed	
Slewing/Deploying	2°/second
Peaking	0.5°/second
Motors	24V DC Variable Speed, Constant Torque
RF Interface	
Waveguide	WR 75 Cover Flange at Interface Point
HPA Mounting	Feed Boom, Rear of reflector, or Inside Vehicle Options
Axis Transition	Rotary Joints for Azimuth, Elevation, Flex in Pol (R/J Option)
Waveguide	WR 75 Cover Flanges at Feed (or Optional Waveguide Integration)
Coax	RG59 run from feed to base plus 25 ft. (8 m)
Electrical Interface	25 ft. (8 m) Cable with Connectors for Controller
Manual Drive	Handcrank on Az and EI Axii, Hand knob on Pol
Weight	230 lbs (105 kg)
Stowed Dimensions	88 L x 62 W x 17.5 H inches (224 L x 157 W x 45 H cm)

Environmental

Wind	
Survival, Deployed	80 mph (129 kmph)
Survival, Stowed	100 mph (161 kmph)
Operational	45 mph (72 kmph), Gusts to 60 mph (97 kmph)

Pointing Loss in Wind	
20 mph (32 kmph)	0.1 dB
30 Gusting to 45 mph (48 to 72 kmph)	0.3 dB Typical, 1 dB Maximum

Temperature	
Operational	+5° to 125°F (-15° to 52°C)
Survival	-40° to 140°F (-40° to 60°C)