

# AVL TECHNOLOGIES

## MODEL 1210K DSNG

### 1.2 METER MOTORIZED VEHICULAR ANTENNA

Reflector	1.2 meter AvL Carbon-Fiber
Feed	Precision Corrugated Horn
Optics	Offset, Prime Focus, .8 f/d
Drive System	Patented Roto-Lok® Positioner
Mount Geometry	Elevation over Azimuth
Polarization Adjustment	Rotation of Feed



#### Electrical RF

Frequency	10.95-12.75 GHz	13.75-14.50 GHz
Gain (Midband)	41.6 dBi	43.2 dBi
2-port	41.5 dBi	43.1 dBi
4-port	1.30:1	1.30:1
VSWR	1.3	1.2
Beamwidth (degrees)	2.4	2.0
-3 dB	-22 dB	-25 dB
-10 dB	>3 dB better than FCC §25.209, ITU-R S.528.5	
First Sidelobe Level (Typical)	43° K at 30° Elevation	
Radiation Pattern Compliance	Linear Orthogonal Standard, Optional Co-pol	
Antenna Noise Temperature	0.5KW per port	
Polarization		
Power Handling Capability		
Cross-Pol Isolation		
On-Axis (minimum)	35 dB	35 dB
Off-Axis (within 1 dB BW)	30 dB	32 dB
Off-Axis (peak)	22 dB	25 dB
Feed Port Isolation – TX to RX	75 dB	
Satellite System Compliance	FCC, Intelsat, Loral Skynet	



#### Receive

#### Transmit

#### Controllers

Standard	Three-axis Jog Control & Display with Auto-stow
Optional Upgrades	
Semi-automatic Operation	Drive to calculated position based on operator entered vehicle location, heading, plus satellite (longitude or listed)
Automatic Operation	Drive to calculated position based on auto GPS and Flux-Gate Compass data and satellite peaking with LNB signal
Auto-acquisition	One-button acquisition of selected satellite including peaking and optimization of cross-pol (certified for auto-commissioning on select services)
Size	Two Rack Units for Semi-automatic & Automatic Controllers Single Rack Unit for Auto-acquisition
Input Power	110/240 VAC, 1 ph, 50/60 Hz, 6/3A peak, 1A continuous

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#### Mechanical

Az/EI Drive System	Patented Roto-Lok® Cable Drive System
Polarization Drive System	Non back-driving Worm Gear
Travel	
Azimuth	400°
Elevation	True elevation readout from calibrated inclinometer
Mechanical	0° to 90° of Reflector Boresight
Electrical	Standard limits at 5° to 65° (CE Approval) or 5° to 90°
Polarization	±95° for 2-port and 3-port Feeds ±50° for 2-port Wideband and 4-port feeds
Speed	
Slewing/Deploying	2°/second
Peaking	0.2°/second
Motors	24V DC Variable Speed, Constant Torque
RF Interface	
HPA Mounting	Feed Boom, Rear of Reflector, or Inside Vehicle
Axis Transition	Twist-Flex or Rotary Joints
Waveguide	WR 75 Cover Flange at Interface Point
Coax	RG59 run from feed to base plus 25 ft. (8 m)
Electrical Interface	25 ft. (8 m) Cable with Connectors for Controller
Manual Drive	Handcrank on Az and EI Axii, Leads from 12VDC Pol Motor
Weight	115 to 125 lbs. (52 to 57 kg) depending on options selected
Stowed Dimensions	74 L x 49 W x 17 H inches (188 L x 125 W x 43 H cm)

#### Environmental

Wind	
Survival	
Deployed	75 mph (121 kmph)
Stowed	100 mph (161 kmph)
Operational	45 mph (72 kmph), Gusts to 60 mph (97 kmph)
Pointing Loss in Wind	
20 mph (32 kmph)	0.2 dB, 0.15 degrees Typical
30 Gusting to 45 mph (48 to 72 kmph)	0.8 dB, 0.30 degrees Typical
Temperature	
Operational	+5° to 125°F (-15° to 52° C)
Survival	-40° to 140°F (-40° to 60° C)