AVL TECHNOLOGIES

MODEL 1212K GLOBAL 1.2 METER MOTORIZED VEHICULAR ANTENNA

Reflector
Feed
Optics
Drive System
Mount Geometry

Polarization Adjustment

1.2 meter AvL Carbon-Fiber Mode-matched with Rotary Joint Offset, Prime Focus, .8 f/d Patented Roto-Lok® Positioner Elevation over Azimuth

Rotation of Feed



Electrical RF	<u>Receive</u>	<u>Transmit</u>
Frequency	10.95-12.75 GHz	13.75-14.5 GHz
Gain (Midband)		
2-port	41.6 dBi	43.2 dBi
4-port	41.5 dBi	43.1 dBi
VSWR	1.30:1	1.30:1
Beamwidth (degrees)		
-3 dB	1.3	1.2
-10 dB	2.3	2.0
First Sidelobe Level (Typical)	-22 dB	-25 dB
Radiation Pattern Compliance	>3 dB better than FCC §25.209, ITU-R S.528.5	
Antenna Noise Temperature	43° K at 30° Elevation	
Polarization	Orthogonal standard, Optional Co-pol	
Power Handling Capability		0.5KW per port
Cross-Pol Isolation		
On-Axis (minimum)	35 dB	35 dB
Off-Axis (within 1 dB BW)	30 dB	35 dB
Off-Axis (peak)	22 dB	30 dB
Feed Port Isolation – TX to RX	75 dB	
Satellite System Compliance	Eutelsat, Intelsat, Asiasat, PanAmSat etc.	

Controllers

Standard Standard	
Optional Upgrades	
Semi-automatic Operation	
Automatic Operation	
Auto-acquisition	

Size

Input Power

Three-axis Jog Control & Display with Auto-stow

Drive to calculated position based on operator entered vehicle location, heading, plus satellite (longitude or listed) Drive to calculated position based on auto GPS and Flux-Gate Compass data and satellite peaking with LNB signal One-button acquisition of selected satellite including peaking and optimization of cross-pol (certified for auto-commissioning on select services)

Two Rack Units for Semi-automatic & Automatic Controllers Single Rack Unit for Auto-acquisition

110/240 VAC, 1 ph, 50/60 Hz, 6/3A peak, 1A continuous

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Mechanical

Az/El Drive System Patented Roto-Lok® Cable Drive System

Polarization Drive System Non back-driving Worm Gear

Travel

Azimuth 400°

Elevation True elevation readout from calibrated inclinometer

Mechanical 0° to 90° of Reflector Boresight

Electrical Standard limits at 5° to 65° (CE Approval) or 5° to 90°

Polarization ±95° for 2-port and 3-port Feeds

±50° for 2-port Wideband and 4-port feeds

Speed

Slewing/Deploying 2°/second Peaking 0.2°/second

Motors 24V DC Variable Speed, Constant Torque

RF Interface

HPA Mounting Feed Boom, Rear of Reflector, or Inside Vehicle

Axis Transition Twist-Flex or Rotary Joints

Waveguide WR 75 Cover Flange at Interface Point
Coax RG59 run from feed to base plus 25 ft. (8 m)

Electrical Interface 25 ft. (8 m) Cable with Connectors for Controller

Manual Drive Handcrank on Az and El Axii, Leads from 12VDC Pol Motor Weight 115 to125 lbs. (52 to 57 kg) depending on options selected

Stowed Dimensions 74 L x 49 W x 17 H inches (188 L x 125 W x 43 H cm)

Environmental

Wind

Survival

Deployed 75 mph (121 kmph) Stowed 100 mph (161 kmph)

Operational 45 mph (72 kmph), Gusts to 60 mph (97 kmph)

Pointing Loss in Wind

20 mph (32 kmph) 0.2 dB, 0.15 degrees Typical 30 Gusting to 45 mph (48 to 72 kmph) 0.8 dB, 0.30 degrees Typical

Temperature

Operational +5° to 125°F (-15° to 52° C) Survival -40° to 140°F (-40° to 60° C)